

# Optimal filtering for bolometer signals in cryogenic particle detectors

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# Overview

- 1 Signal processing
- 2 Software implementation

# Signal characteristics

- signals are at low frequencies.
- significant amount of  $1/f$  noise (flicker noise) due to instability in the experiment/hardware conditions
- $1/f^0$  (white noise) due to electronics' noise
- noise from power line/radio frequency/ground loops at “fixed” frequencies (may vary with the configuration)
- unavoidable noise of different nature due to statistical fluctuations in system

# Methods to suppress the noise

- $1/f$  (flicker)- hardware stabilization (wait a long time before experiment); short accusation time, (filtering?)
- pickup noise- proper power supply and grounding systems; avoiding loops; accurate choosing of experimental time; filtering
- white noise- choosing the low noise electronics; filtering
- unavoideble noise statistical noise - filtering

# Assumptions for signal filtering

- the pulses  $D(t)$  have the same shape  $H \cdot S(t)$ ,  $H$ - the amplitude,  $S(t)$ - the known pulse shape
- system is linear;  $S(t)$  does not depend on  $H$
- the random noise has known stationary spectral power  $N_f^2$ , uncorelated at different  $f$

# Signal filtering I

Dan McCammon "Thermal Equilibrium Calorimeters- An Introduction"

Discrete Fourier transform of  $D_f = FFT(D(t))$

Root mean square value of the noise  $N_f$

Each  $D_f \sim H$  and provides an independent estimate for  $H$

Then  $H = \sum w_f \cdot D_f$

Noise fluctuation  $\Delta H_{rms} = \sqrt{\sum (w_f \cdot N_f)^2}$

$\frac{H}{\Delta H_{rms}} = \max \Rightarrow w_f = \frac{D_f}{N_f^2} (\sum (w_f \cdot N_f)^2 / \sum w_f \cdot D_f)$

remove common scale factor  $\Rightarrow w_f = \frac{D_f}{N_f^2}$

choose phases to maximize the numerator in  $\frac{H}{\Delta H_{rms}} \Rightarrow w_f = \frac{D_f^*}{N_f^2}$

remove common scale factor  $H \Rightarrow w_f = \frac{S_f^*}{N_f^2}$  and  $H \sim \sum \frac{D_f \cdot S_f^*}{N_f^2}$

# Signal filtering II

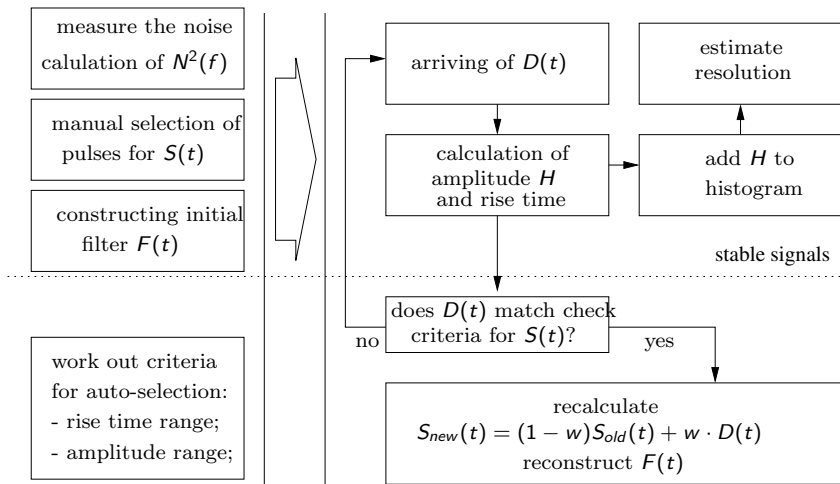
A. E. Szymkowiak "Signal Processing for Microcalorimeters"

$$\chi^2 = \sum \frac{|D_f - H \cdot S_f|^2}{N_f^2} = \sum \frac{(D_f - H \cdot S_f) \cdot (D_f - H \cdot S_f)^*}{N_f^2}$$

$$\partial \chi^2 / \partial H = 0 \Rightarrow 2H \sum \frac{S_f S_f^*}{N_f^2} = \sum \frac{D_f S_f^* + D_f^* S_f}{N_f^2}$$

because of  $S(t)$  and  $D(t)$  are Real  $\Rightarrow H = \sum \frac{D_f \cdot S_f^*}{N_f^2} / \sum \frac{S_f S_f^*}{N_f^2}$   
 finally, to avoid FFTs  $H = \sum D(t)F(t) / \sum S(t)F(t)$  where filter  
 $F(t) = FFT^{-1}(\frac{S_f^*}{N_f^2})$

# Processing algorithm





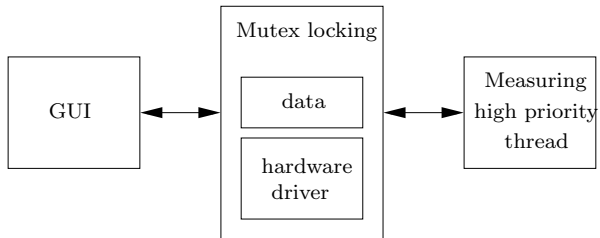
# Software demands

- fast data taking from digitizer on fly; controlling of acquisition/oscilloscope parameters (sampling rate, coupling etc.)
- data visualization (signal, FFT, energy spectrum)
- data processing on/off fly
- data saving/reading into/from hard disk

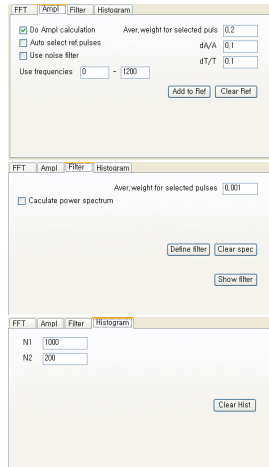
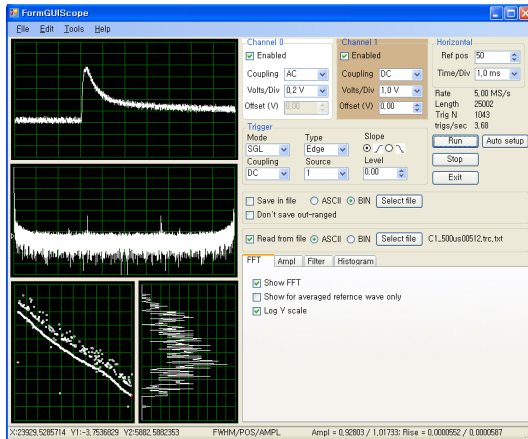
# Software design

- real time multi-thread application with mutex locking synchronization
- MS Visual C++ Net Framework 2
- NI's high frequency digitizer driver
- external OS FFT library- FFTW3, compiled with MinGW

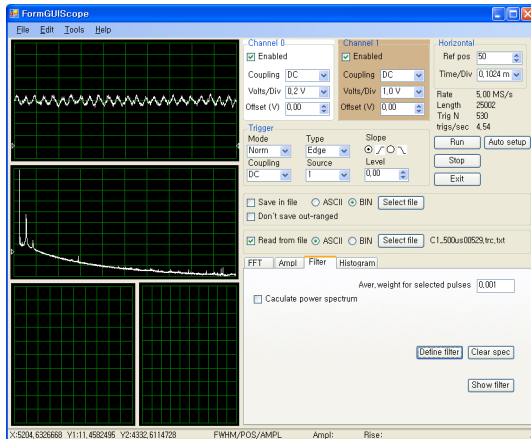
# Software architecture



## Software GUI



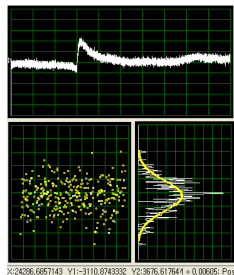
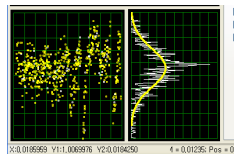
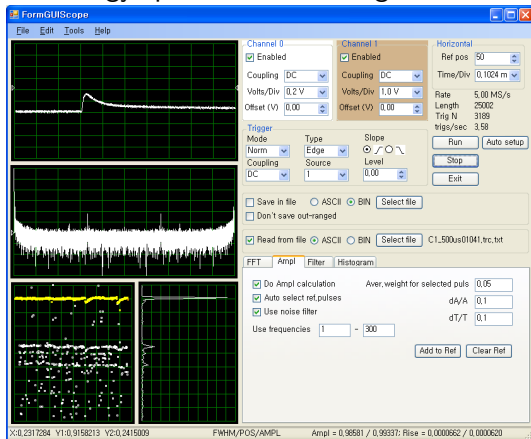
# Application example



noise power  
spectrum

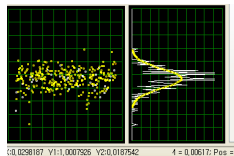
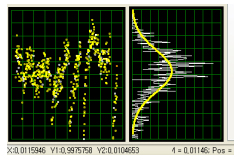
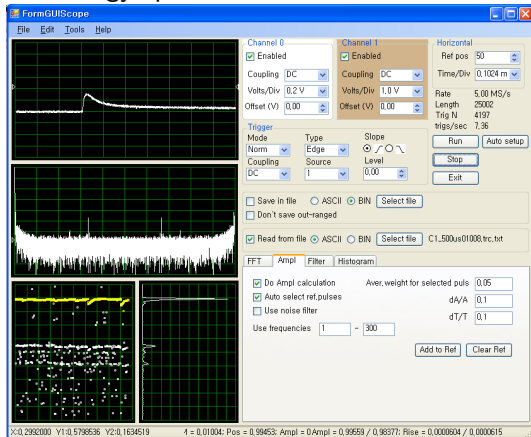
# Application example I

the energy spectrum with using filter



# Application example II

the energy spectrum without filter



# Plans

- program support
- implementation new features on demand