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### DNN(FCN) for GBAR experiment Monte Carlo simulation data
# 100,000 raw datas of signals by annihilation of upward, downward gravitation and ↗
background signals each.
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import numpy as np
import matplotlib as plt
import random
import uproot
import h5py

import tensorflow as tf
from keras import models
from keras import layers
from keras.utils import to_categorical
from keras.utils.io_utils import HDF5Matrix
import keras.backend.tensorflow_backend as K

filename = "SignalMCwaveform_flatten.hdf5"

X_train = HDF5Matrix(filename, 'X_train')
X_test = HDF5Matrix(filename, 'X_test')
Y_train = HDF5Matrix(filename, 'Y_train')
Y_test = HDF5Matrix(filename, 'Y_test')

# Use gpu as processor
with K.tf.device("/device:GPU:0"):

    # Sequential model
    model = models.Sequential()

    ## Change the number of 'hidden layers' and 'neurons'.

    # The first hidden layer
    model.add(layers.Dense(2048, activation='relu', input_shape=(112*88,)))
    model.add(layers.Dropout(0.2))

    # The second hidden layer
    model.add(layers.Dense(2048))
    model.add(layers.Activation('relu'))
    model.add(layers.Dropout(0.2))

    # The third hidden layer
    model.add(layers.Dense(2048))
    model.add(layers.Activation('relu'))
    model.add(layers.Dropout(0.2))

    # The fourth hidden layer
    model.add(layers.Dense(2048))
    model.add(layers.Activation('relu'))
    model.add(layers.Dropout(0.2))
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# The fifth hidden layer
model.add(layers.Dense(2048))
model.add(layers.Activation('relu'))
model.add(layers.Dropout(0.2))

# The final layer
model.add(layers.Dense(3, activation='softmax'))

# Compile
# Change 'epochs' and 'batch_size'
model.compile(optimizer = 'adam',
              loss = 'categorical_crossentropy',
              metrics=['accuracy'])

model.fit(X_train, Y_train, epochs = 7, shuffle = 'batch', batch_size = 2048,
         verbose = 1)
test_loss, test_acc = model.evaluate(X_test, Y_test)
print('test_acc : ', test_acc)

'''
# Save the model
# model.save("FCN_1.h5")
'''
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